**/PROG MAIN\_VIS\_PICK**

LINE\_TRACK;

LINE\_TRACK\_SCHEDULE\_NUMBER : 1;

LINE\_TRACK\_BOUNDARY\_NUMBER : 0;

CONTINUE\_TRACK\_AT\_PROG\_END : FALSE;

/MN

1: ;

2: PR[23,2:Vision\_Offset]=PR[R[56],2] ;

3: ;

4: PR[23,6:Vision\_Offset]=PR[R[56],6] ;

5: ;

6:L P[2] 650mm/sec CNT25 Offset,PR[23:Vision\_Offset] ;

7: ;

8: WAIT .25(sec) ;

9:L P[1] 500mm/sec FINE Offset,PR[23:Vision\_Offset] ;

10: ;

11: WAIT .25(sec) ;

12: DO[2:Vacuum\_Y2]=ON ;

13: WAIT .25(sec) ;

14: ;

15:L P[2] 650mm/sec CNT25 Offset,PR[23:Vision\_Offset] ;

16: ;

17: R[56:Offset\_Counter]=R[56:Offset\_Counter]+1 ;

18: ;

19: IF R[56:Offset\_Counter]<=39,JMP LBL[20] ;

20: ;

21: R[56:Offset\_Counter]=30 ;

22: LBL[20] ;

/POS

P[1]{

GP1:

UF : 0, UT : 0, CONFIG : ', , 0',

X = -472.000 mm, Y = -18.000 mm, Z = 11.000 mm,

W = 180.000 deg, P = 0.000 deg, R = 109.707 deg

};

P[2]{

GP1:

UF : 0, UT : 0, CONFIG : ', , 0',

X = -470.000 mm, Y = -18.000 mm, Z = 35.000 mm,

W = 180.000 deg, P = 0.000 deg, R = 109.707 deg

};

/END